

Multi Slider Swift

User Manual

Version 1.0



Table of Contents

1.	Introduction1
2.	System Overview and Components 2
3.	Technical Data
3.1	Carriage
3.2	Track 3
4.	Handling 4
4.1	Radius Adjustment 4
4.2	Mounting the Track 5
4.2.	Mounting the Track to Tripods
4.3	Connecting the Cables
4.3.	L Supply
4.3.	2 Control line 7
4.3.	HMI Control Unit with Joystick or food pedals
5.	Operation9
5.1	Initialization of the slider via HMI Control Unit9
5.2	Operating the slider via HMI Control Unit10
6.	Handling and Safety Instructions 11
6.	1 Regulatory Hints 12



1. Introduction

The Multi Slider Swift is a bendable camera slider for professional use. Developed by professional cameramen, the Multi Slider Swift enables linear and curved camera tracks with one device. Within seconds the Multi Slider Swift can be changed from a linear to a curved slider at any desired radius.





2. System Overview and Components

All Multi Slider Swift systems include:

- Track with rails and mounted end parts.
- Carriage that moves on the rails and includes the drive with motor and XL Control
 unit.
- XL Control Unit Controls the System with Sensors, Motor and User Inputs see separate manual for details for the XL Control Unit
- Power Supply Supplies the motor and control unit of the MS Swift

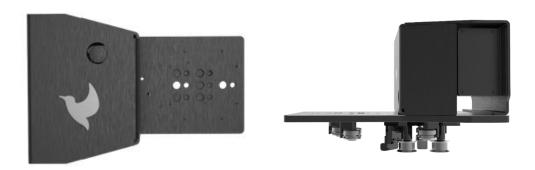
Optional:

- Tripods that allow to mount the track elevated above the ground level
- Battery pack: Rechargeable lithium-ion battery allows the System to be operated without the need for a power supply cable and in locations where no power supply is available
- HMI Unit with joystick or foot pedals allows to control the MS Swift via manual control



3. Technical Data

3.1 Carriage



Dimensions:	250 x 160 x 155 (L x W x H) [mm]
Material:	Aluminum black anodized surface finish

3.2 Track



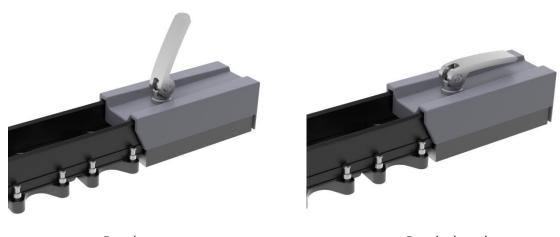
Hight:	186 [mm] total hight from bottom to top of carriage
Length	made to order, up to 100m
Material:	Glass fiber reinforced plastic + stainless steel inlays
Material:	Aluminum black anodized surface finish



4. Handling

4.1 Radius Adjustment

Before adjusting the radius / bending the slider in any way always release the breaks of the Multi Slider on both ends. Only bend with breaks opened. After bending to the desired radius or to a straight slider fix the system by closing the breaks.



Break open Break closed

The radius of any Multi Slider can be adjusted up to 25 cm for filming/photographs. Don't bend the slider while the slide is being moved. When transporting the Multi Slider can be bent more for a smaller pack size.



4.2 Mounting the Track

The slider can easily be mounted on tripods. Each segment of the Multi Slider Swift has a 3/8" UNC thread on the bottom. Depending on the weight of the camera and head used for filming more tripods may be necessary. Always make sure that balance point of the camera and head mounted on the slide is in the center.





4.2.1 Mounting the Track to Tripods

First mount the tripod adapter plate by screw to the thread of segments (spigot adapter plate ensures high stability and comes with waterbird tripods or can be ordered separately)



It is recommended to have a support tripod or pole every 5-6 segments for lightweight loads like PTZ cameras or every 3 segments for heavy loads.

Finally connect the track to the tripods by sliding in the adapter plates into the tripods and fix it with tripod locking screw.



4.3 Connecting the Cables

4.3.1 Supply

Connect white connector of the sliders power supply to the power cable that comes with your slider. The other end of the power cable shall be connected to the D-Tap connector on the carriage.

For strain relief use the included cable bracket and mount the power supply cable via a hookand-loop tape or cable tie.

After connecting the DC-side of the power supply the AC side can be connected to the mains supply.

For this use a standard IEC 60320 C14 cable and connect it to a properly grounded wall socket.

4.3.2 Control line

The Multi Slider Swift comes with the XL Motion Controller. This controller allows to control the slider movements via standard DMX 512 protocol or via Ethernet.

For details of the XL Motion Controller and its capabilities, please see the separate XL Motion Controller User Manual available in the support section of www.waterbird.at

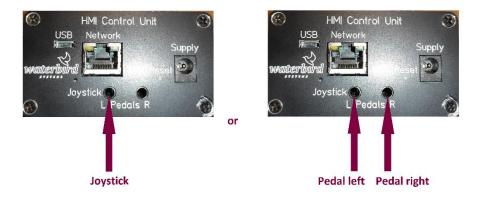
Depending on your chosen way of control connect the DMX or RJ45 cable to the XL Motion Controller mounted on the carriage and strain relief with the included cable bracket alongside with the power cable.



4.3.3 HMI Control Unit with Joystick or food pedals

For manual control of the slider the optional available HMI control unit needs to be connected to the DMX cable.

Next the joystick or food pedals need to be connected to the HMI unit:



After DMX cable and Joystick or food pedals have been connected put the included HMI power supply on the Supply Jack of the HMI Unit and use a standard IEC 60320 C14 cable to connect the power supply to a properly grounded wall socket



5. Operation

5.1 Initialization of the slider via HMI Control Unit

After connecting all cables and powering up the system the slider does not respond to commands from the joystick or food pedals. This is because it needs to be referenced first.

For this hold down the "Ref run" button for longer than 3 seconds. The "Ref run" button will light up for one second and the slider begins to move and automatically references via the magnets on each end of the slider.



After the refence run is finished the motor stops and the control via Joystick or food pedals is possible.

You can de-initialize the slider anytime by pressing the "Ref run" button for shorter than 3 seconds. This will suddenly stop the motor and should only be done when the motor is not moving or in the need for an emergency stop.

At deinitialization the controller un-powers the motor and invalidates the current position. Therefore, a new initialization run is necessary after each deinitialization.



5.2 Operating the slider via HMI Control Unit

After the slider is initialized you can move the Joystick / Food Pedals to get the slider in motion.

The Max speed knob on the HMI Unit can be used to set the maximal speed that is used when moving the Joystick to the full left or right position or fully pressing the food pedal.

The Acceleration knob on the HMI Unit sets the ramp of how the carriage is accelerated when moving the Joystick/pressing the Food pedals. A lower value means a softer start, a higher value results in faster accelerations.

Maximum speed and acceleration shall be aligned to the application and payload.

The "Auto PingPong" button can be pressed to activate the automatic movement from one end of the slider to the other continuously. This can by a useful feature for situations you have no operator for the slider but want to have some movement in your pictures like at interviews, live casting, or event recordings.

While the PingPong function is on, the "Auto PingPong" button lights up and the inputs of the Joystick/Food pedals is ignored. Also, during the PingPong function you can control the sliders speed and acceleration behavior via the Max Speed and Acceleration knobs.

For deactivating the PingPong function press again onto the "Auto PingPong" button.



6. Handling and Safety Instructions

When carrying the slider grab the whole system, never put fingers between the rails and the single segments. Fingers must be outside of the rails to avoid pinching.

Always lock the Multi Slider while transporting it. Give it a fixed shape and make sure that the shape is not changed during transport.

When moving the slide make sure that there are no fingers, hands, or any other objects on the rails, segments or somewhere else on the system.

Do not use the product in wet or humid environment like rain, snow, spray or waterfalls without extra protection against humidity intrusion into the carriage.

Do not install this Unit near a heater, inflammable material or oily or dusty location or in a location continuously exposed to direct sunlight or in a location where gas may leak.

Remove all foreign substances such as dust or water from the product with a dry cloth on a regular basis. - Clean it with a dry cloth without alcohol or other solvents.

Do not pull or excessively bend the cables. Do not twist or tie the cables. Do not hook the cables over a metal object or place a heavy object on the cables. Do not pull the cables, when unplugging. Pull out the cable only by holding the plug. Do not put force on the cables in any direction when connected to the Control Unit or Motor, this can damage the Control Unit or Motor and connectors.

Before switching on the power to the product ensure that the Motors can spin freely and no harm to humans, animals or objects is possible in case the connected motors start moving.

Do not use the product if it is damaged, the isolation on the cables is damaged or it shows any abnormality like excessive heat dissipation.

It is normal that the Control Unit and Motor gets warm during operation. To avoid overheating do not cover the Control Unit or Motor with thermally insulating material and allow free airflow.



6.1 Regulatory Hints



INSTRUCTION ABOUT THE WEEE MARK

Correct Disposal of This Product (Waste Electrical & Electronic Equipment) (Applicable in countries with separate collection systems) This marking on the product, accessories or literature indicates that the product and its electronic accessories (cables, adapters,..) should not be disposed of with other household

waste at the end of their working life. To prevent possible harm to the environment or human health from uncontrolled waste disposal, please separate these items from other types of waste and recycle them responsibly to promote the sustainable reuse of material resources. Household users should contact either the retailer where they purchased this product, or their local government office, for details of where and how they can take these items for environmentally safe recycling. Business users should contact their supplier and check the terms and conditions of the purchase contract. This product and its electronic accessories should not be mixed with other commercial wastes for disposal.

USA:

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy, and if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- · Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.



Canada:

This device complies with Industry Canada's licenseexempt RSSs. Operation is subject to the following two conditions:

- (1) This device may not cause interference; and
- (2) This device must accept any interference, including interference that may cause undesired operation of the device.

Le présent appareil est conforme aux CNR d'Industrie Canada applicables aux appareils radio exempts de licence. L'exploitation est autorisée aux deux conditions suivantes:

- (1) l'appareil ne doit pas produire de brouillage;
- (2) l'utilisateur de l'appareil doit accepter tout brouillage radioélectrique subi, même si le brouillage est susceptible d'en compromettre le fonctionnement.

China:

注意!

依據 低功率電波輻射性電機管理辦法 第十二條 經型式認證合格之低功率射頻電機, 非經許可.

公司、商號或使用者均不得擅自變更頻率、加大功率或變更原設計

之特性及功能。

第十四條 低功率射頻電機之使用不得影響飛航安 全及干擾合法通信:

經發現有干擾現象時,應立即停用,並改善至無 干擾時方得繼續使用。

前項合法通信,指依電信規定作業之無線電信。 低功率射頻電機須忍受合法通信或工業、科學及 醫療用電波輻射性

電機設備之干擾。